

## COURSE OUTLINE

### **Mathematics 108H (C-ID Number: Math 240) Honors Ordinary Differential Equations (C-ID Title: Ordinary Differential Equations)**

#### **Catalog Statement**

MATH 108 covers the solution of ordinary differential equations using various techniques including variation of parameters, the Laplace transform, power series, and numerical methods. Systems of linear differential equations and an introduction to nonhomogeneous linear systems are also covered. Applications are drawn from the physical sciences. The honors section of this course features more theory and proof, and one or more projects related to the topics of this course.

Total Lecture Units: 5.0

Total Laboratory Units: 0.0

**Total Course Units: 5.0**

Total Lecture Hours: 80.0

Total Laboratory Hours: 0.0

Total Laboratory Hours To Be Arranged: 0.0

**Total Faculty Contact Hours: 80.0**

Prerequisite: MATH 104

Recommended Preparation: MATH 105

#### **Course Entry Expectations**

Prior to enrolling in the course, the student should be able to:

- graph logarithmic and exponential functions;
- graph equations in polar parametric form;
- graph conic sections;
- integrate functions using variety of techniques;
- differentiate inverse trigonometric functions;
- apply L'Hospital's rule to find limits of indeterminate forms;
- evaluate improper integrals;
- model differential equations;
- solve separable differential equations;
- solve differential equations using slope fields and Euler's Method;
- work with exponential and logistic models of growth and decay;
- determine divergence or convergence of infinite series;
- differentiate and integrate power series;
- find Taylor and Maclaurin series for a function.

## **Course Exit Standards**

Upon successful completion of the required coursework, the student will be able to:

- select the appropriate method of solution, given a list of first order differential equations;
- solve both homogeneous and nonhomogeneous differential equations with constant coefficients of second or higher order;
- use the Laplace transform to solve nonhomogeneous differential equations with constant coefficients and initial conditions;
- use power series to solve differential equations with variable coefficients;
- use eigenvalues of matrices to solve systems of linear differential equations;
- approximate solutions to first order differential equations by using numerical methods on a computer;
- apply the techniques of solution to applications from at least two different areas of the physical sciences.

## **Course Content**

**Total Faculty Contact Hours = 80.0**

### **Introduction to Differential Equations (4 hours)**

Some basic mathematical models: Direction fields  
Solutions of some differential equations  
Classification of differential equations

### **First Order Differential Equations (16 hours)**

Linear equations with variable coefficients  
Separable equations  
Modeling with first order equations  
Differences between linear and nonlinear equations  
Autonomous equations and population dynamics  
Exact equations and integrating factors  
Numerical approximations: Euler's method  
The existence and uniqueness theorem

### **Second Order Linear Equations (12 hours)**

Homogeneous equations with constant coefficients  
Fundamental solutions of linear homogeneous equations  
Linear independence and the Wronskian  
Complex roots of the characteristic equation  
Repeated roots; reduction of order  
Nonhomogeneous equations: Method of undetermined coefficients  
Variation of parameters  
Mechanical and electrical vibrations  
Forced vibrations

### **Series Solutions of Second Order Linear Equations (12 hours)**

Review of power series  
Series solutions near an ordinary point  
Regular singular points  
Euler equations

### **The Laplace Transform (10 hours)**

Definition of the Laplace transform

Solutions of initial value problems  
Step functions  
Differential equations with discontinuous forcing functions  
Impulse functions  
The convolution integral

**Systems of First Order Linear Equations (15 hours)**

Review of matrices  
Systems of linear algebraic equations: Linear independences, eigenvalues, eigenvectors  
Basic theory of systems of first order linear equations  
Homogeneous linear systems with constant coefficients  
Complex eigenvalues  
Fundamental matrices  
Repeated eigenvalues  
Nonhomogeneous linear systems

**Numerical Methods (6 hours)**

The Euler or tangent line method  
Improvements on the Euler method  
The Runge-Kutta method

**Partial Differential Equations and Fourier Series (5 hours)**

At least two of the following topics should be covered by the instructor:  
Two-point boundary value problems  
Fourier series  
The Phase Plane: Linear Systems  
Autonomous systems and stability  
Series solutions near a regular point  
Bessel's equations

**Methods of Instruction**

The following methods of instruction may be used in this course:

- lectures/discussions;
- computer (or other technological) explorations;
- group work/student presentations;
- online presentations.

**Out of Class Assignments**

The following out of class assignments may be used in this course:

- homework (e.g. problem sets related to course content);
- projects (e.g. prove a theorem stated in the textbook and present the proof to the instructor).

**Methods of Evaluation**

The following methods of evaluation may be used in this course:

- quizzes;

- in-class presentations;
- four or more exams are required;
- a comprehensive final examination is required.

### **Textbooks**

Nagle, R. Kent, and Edward B. Saff, and Arthur D. Snider. *Fundamentals of Differential Equations and Boundary Value Problems*. 6<sup>th</sup> ed. Boston: Addison-Wesley, 2012. Print. 15<sup>th</sup> Grade Textbook Reading Level. ISBN #978-0-321-74774-7

### **Student Learning Outcomes**

Upon successful completion of the required coursework, the student will be able to:

- solve a variety of rudimentary first and second order linear and non-linear differential equations;
- utilize series solutions around ordinary points and regular singular points in order to solve second order linear differential equations;
- utilize Laplace transforms in order to solve initial value problems;
- solve systems of homogeneous and non-homogeneous linear differential equations using matrix methods;
- utilize numerical methods to solve first order differential equations.