

## ENGR130 : Introduction to Robotics

### General Information

Author:	<ul style="list-style-type: none"><li>Christopher Herwerth</li></ul>
Course Code (CB01) :	ENGR130
Course Title (CB02) :	Introduction to Robotics
Department:	ENGR
Proposal Start:	Spring 2025
TOP Code (CB03) :	(0924.00) Engineering Technology, General (requires Trigonometry)
CIP Code:	(15.0000) Engineering Technologies/Technicians, General.
SAM Code (CB09) :	Possibly Occupational
Distance Education Approved:	No
Will this course be taught asynchronously?:	No
Course Control Number (CB00) :	CCC000620918
Curriculum Committee Approval Date:	06/12/2024
Board of Trustees Approval Date:	10/15/2024
Last Cyclical Review Date:	06/12/2024
Course Description and Course Note:	ENGR 130 provides an introductory study of the fundamentals of mobile robotics, robotic arms, and the associated engineering concepts. It prepares students for more advanced studies in robotics and related technologies. Students gain experience with fundamental concepts in robot design, sensors and actuators, programming, electronics, and computer aided design and 3D printing. The vast majority of the course experience consists of implementation of and experimentation with these skills through hands-on labs.
Justification:	Mandatory Revision
Academic Career:	<ul style="list-style-type: none"><li>Credit</li></ul>
Mode of Delivery:	No value
Author:	<ul style="list-style-type: none"><li>Christopher Herwerth</li></ul>
Course Family:	No value

### Academic Senate Discipline

Primary Discipline:	<ul style="list-style-type: none"><li>Engineering Technology</li></ul>
Alternate Discipline:	No value
Alternate Discipline:	No value

## Course Development

### Basic Skill Status (CB08)

Course is not a basic skills course.

Allow Students to Gain Credit by Exam/Challenge

### Course Special Class Status (CB13)

Course is not a special class.

### Pre-Collegiate Level (CB21)

Not applicable.

### Grading Basis

- Grade with Pass / No-Pass Option

### Course Support Course Status (CB26)

Course is not a support course

## General Education and C-ID

### General Education Status (CB25)

Not Applicable

### Transferability

Transferable to CSU only

### Transferability Status

Approved

## Units and Hours

### Summary

<b>Minimum Credit Units (CB07)</b>	2
<b>Maximum Credit Units (CB06)</b>	2
<b>Total Course In-Class (Contact) Hours</b>	72
<b>Total Course Out-of-Class Hours</b>	36
<b>Total Student Learning Hours</b>	108

### Credit / Non-Credit Options

#### Course Type (CB04)

Credit - Degree Applicable

#### Noncredit Course Category (CB22)

Credit Course.

#### Noncredit Special Characteristics

No Value

#### Course Classification Code (CB11)

Credit Course.

Variable Credit Course

#### Funding Agency Category (CB23)

Not Applicable.

Cooperative Work Experience Education

Status (CB10)

### Weekly Student Hours

	In Class	Out of Class
Lecture Hours	1	2
Laboratory Hours	3	0
Studio Hours	0	0

### Course Student Hours

<b>Course Duration (Weeks)</b>	18
<b>Hours per unit divisor</b>	54
<b>Course In-Class (Contact) Hours</b>	
Lecture	18

Laboratory	54
Studio	0
<b>Total</b>	72

**Course Out-of-Class Hours**

Lecture	36
Laboratory	0
Studio	0
<b>Total</b>	36

**Time Commitment Notes for Students**

No value

**Units and Hours - Weekly Specialty Hours**

Activity Name	Type	In Class	Out of Class
No Value	No Value	No Value	No Value

**Pre-requisites, Co-requisites, Anti-requisites and Advisories**

**Advisory**

ESL141 - Grammar And Writing IV

Objectives

- Compose a 400 to 450-word thesis-based essay which: (a) summarizes and cites appropriately a reading passage provided as a prompt, (b) includes a clear thesis statement, (c) uses evidence to support the thesis, (d) shows clear organization into an introduction, body, and conclusion, and (e) uses appropriate rhetorical modes such as comparison/contrast, cause/effect, and persuasion in order to support a thesis.

**OR**

**Advisory**

ENGL101 - Introduction to College Reading and Composition

Objectives

- Read, analyze, and evaluate a variety of primarily non-fiction readings for content, context, and rhetorical merit with consideration of tone, audience, and purpose.

**AND**

**Advisory**

MATH100 - College Algebra for STEM

Objectives

- Perform operations on functions.
- Solve equations including: linear, polynomial, radical, rational, absolute value, exponential and logarithmic.

- Model and solve STEM application problems.

## Entry Standards

Entry Standards

## Course Limitations

Cross Listed or Equivalent Course

## Specifications

### Methods of Instruction

Methods of Instruction                      Lecture

Methods of Instruction                      Laboratory

Methods of Instruction                      Discussion

Methods of Instruction                      Collaborative Learning

Methods of Instruction                      Demonstrations

### Out of Class Assignments

- Homework (e.g. carrying-out calculations related to a robot design, such as torque or gear ratios)
- Individual project (e.g. work on a robot design, possibly in 3D CAD software if available, to be implemented during class)
- Group project (e.g. work on a robot design, possibly in 3D CAD software if available, to be implemented during class)

**Methods of Evaluation**

Activity (answering journal prompt, group activity)

Presentation (group or individual)

Activity (answering journal prompt, group activity)

Presentation (group or individual)

**Rationale**

Performance-based assessment of student designed/built robots

Midterm project presentation

Instructor evaluation of student portfolio work

Final project presentation

**Textbook Rationale**

No Value

**Textbooks****Author****Title****Publisher****Date****ISBN**

Andy Lindsay

Robotics with the Board of Education Shield-Bot for Arduino

Parallax

2020

9781928982531

**Other Instructional Materials (i.e. OER, handouts)**

No Value

**Materials Fee**

No value

**Learning Outcomes and Objectives****Course Objectives**

Program and operate various types of robots.

Demonstrate skills of fundamental concepts in robot design.

Demonstrate basic skills in computer aided drafting and design.

Effectively build functional electronic circuits.

Program and operate a robotic arm.

Compose a program that will control a mobile robot to complete tasks successfully, including the integration of sensing, sensor-data processing, and robot action.

## SLOs

### Utilize basic principles of mechanics to design robots.

Expected Outcome Performance: 70.0

<i>ILOs</i> Core ILOs	Analyze and solve problems using critical, logical, and creative thinking; ask questions, pursue a line of inquiry, and derive conclusions; cultivate creativity that leads to innovative ideas.
	Demonstrate depth of knowledge in a course, discipline, or vocation by applying practical knowledge, skills, abilities, theories, or methodologies to solve unique problems.
<i>ENGR</i> Civil Engineering	Apply knowledge of mathematics, science and engineering; identify, form and solve engineering problems
	Demonstrate introductory skills using modern engineering tools necessary for engineering practice.
<i>ENGR</i> Engineering Technology - CAD & Design Drafting	Demonstrate skills in the production of working drawings of engineering structures
<i>ENGR</i> Engineering Entrepreneurship Skill Award	Learn hands-on skills and problem solving techniques for businesses related to engineering design, installation, manufacturing, testing, technical sales, maintenance, and other such topics in engineering technology.
	Learn the engineering design process and how technical products are made, assembled, and integrated into complex systems.
<i>ENGR</i> Computer Engineering AS	analyze engineering problems and make appropriate decisions with the supervision of a licensed engineer;
	design a system, component, or process with supervision of a licensed engineer to meet desired needs.
<i>ENGR</i> Electrical Engineering A.S. Degree Major	analyze engineering problems and make appropriate decisions with the supervision of a licensed engineer;
	design a system, component, or process with supervision of a licensed engineer to meet desired needs.
	use science and mathematical skills required for occupational needs;
<i>ENGR</i> Mechanical Engineering - A.S. Degree Major	design a system, component, or process with supervision of a licensed engineering to meet desired needs.
	use science and mathematical skills required for occupational needs;

### Integrate multidisciplinary topics or direct current (DC) circuits, programming and mechanics for robotic interaction with the physical environment.

Expected Outcome Performance: 70.0

<i>ILOs</i> Core ILOs	Analyze and solve problems using critical, logical, and creative thinking; ask questions, pursue a line of inquiry, and derive conclusions; cultivate creativity that leads to innovative ideas.
	Demonstrate depth of knowledge in a course, discipline, or vocation by applying practical knowledge, skills, abilities, theories, or methodologies to solve unique problems.
<i>ENGR</i> Civil Engineering	Apply knowledge of mathematics, science and engineering; identify, form and solve engineering problems
	Demonstrate introductory skills using modern engineering tools necessary for engineering practice.
<i>ENGR</i> Engineering Entrepreneurship Skill Award	Learn hands-on skills and problem solving techniques for businesses related to engineering design, installation, manufacturing, testing, technical sales, maintenance, and other such topics in engineering technology.
	Learn the engineering design process and how technical products are made, assembled, and integrated into complex systems.

<i>ENGR</i> Computer Engineering AS	analyze engineering problems and make appropriate decisions with the supervision of a licensed engineer; use science and mathematical skills required for occupational needs;
<i>ENGR</i> Electrical Engineering A.S. Degree Major	design a system, component, or process with supervision of a licensed engineer to meet desired needs. use science and mathematical skills required for occupational needs;
<i>ENGR</i> Mechanical Engineering - A.S. Degree Major	design a system, component, or process with supervision of a licensed engineering to meet desired needs. use science and mathematical skills required for occupational needs;

**Compose code that will control a mobile robot and robotic motion.**

Expected Outcome Performance: 70.0

<i>ILOs</i> Core ILOs	Analyze and solve problems using critical, logical, and creative thinking; ask questions, pursue a line of inquiry, and derive conclusions; cultivate creativity that leads to innovative ideas.  Demonstrate depth of knowledge in a course, discipline, or vocation by applying practical knowledge, skills, abilities, theories, or methodologies to solve unique problems.
<i>ENGR</i> Civil Engineering	Apply knowledge of mathematics, science and engineering; identify, form and solve engineering problems  Demonstrate introductory skills using modern engineering tools necessary for engineering practice.
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<i>ENGR</i> Electrical Engineering A.S. Degree Major	analyze engineering problems and make appropriate decisions with the supervision of a licensed engineer; design a system, component, or process with supervision of a licensed engineer to meet desired needs. use science and mathematical skills required for occupational needs;
<i>ENGR</i> Mechanical Engineering - A.S. Degree Major	analyze engineering problems and make appropriate decisions with the supervision of a licensed engineer; design a system, component, or process with supervision of a licensed engineering to meet desired needs. use science and mathematical skills required for occupational needs;
<i>ENGR</i> Computer Engineering AS	analyze engineering problems and make appropriate decisions with the supervision of a licensed engineer; use science and mathematical skills required for occupational needs;

## Additional SLO Information

**Does this proposal include revisions that might improve student attainment of course learning outcomes?**

No

**Is this proposal submitted in response to learning outcomes assessment data?**

No

**If yes was selected in either of the above questions for learning outcomes, explain and attach evidence of discussions about learning outcomes.**

No Value

## SLO Evidence

No Value

## Course Content

### Lecture Content

#### Introduction to Robotics in General, Software, and Hardware (1 hour)

- Historic development of robotics
- Technology that enables automation
- Applications and examples of robotics

#### Fundamental Mechanical Aspects of Robotics (4 hours)

- Basics of motion
- Friction forces
- Relative motion

#### Mechanical Design (4 hours)

- Structure
- Wheels

#### Programming (5 hours)

- Algorithm
- Simple code
- Basic principles of electronic circuits

#### Programming Language Structure and Syntax (1 hour)

- Motion programming and wait commands
- Reading sensors (touch sensors, encoders, ultrasonic sensors)
- Program structures - loops, if-then, switch-case

#### Breadboard-Based Robot Assembly (3 hours)

- Circuit layout
- Circuit elements

**Total Hours: 18**

### Laboratory/Studio Content

#### Robotics Application (2 hours)

- Introduction to sensors, actuators, and controls

#### Speed, Power, Torque, and DC Motors (10 hours)

- Gears, gear ratios, and compound gearing
- Friction and traction

#### Mechanical Design (1 hour)

- Structure
- Wheels

#### Drivetrain Design (12 hours)

- Mechanical design challenge
- Introduction to Autodesk Inventor 3D CAD modeling software

#### Programming Language Structure and Syntax (12 hours)

- Motion programming and wait commands
- Reading sensors (touch sensors, encoders, ultrasonic sensors)
- Program structures - loops, if-then, switch-case

#### Breadboard-Based Robot Assembly (3 hours)

- Circuit layout
- Circuit elements
- Power source



**Programming (14 hours)**

- Basic principles of electronic circuits
- Writing code for motion
- Troubleshooting

**Total Hours: 54****Additional Information**

Is this course proposed for GCC Major or General Education Graduation requirement? If yes, indicate which requirement in the two areas provided below.

No

**GCC Major Requirements**

No Value

**GCC General Education Graduation Requirements**

No Value

**Repeatability**

Not Repeatable

**Justification (if repeatable was chosen above)**

No Value

**Resources**

Did you contact your departmental library liaison?

No

If yes, who is your departmental library liaison?

No Value

Did you contact the DEIA liaison?

No

Were there any DEIA changes made to this outline?

No Value

If yes, in what areas were these changes made:

No Value

**Will any additional resources be needed for this course? (Click all that apply)**

No Value

**If additional resources are needed, add a brief description and cost in the box provided.**

No Value